
The MGS project

- Language dedicated to the simulation of $(DS)^2$
- Declarative (declarative simulation vs procedural)
- Abstract rewriting of complex spatial structures:
 - Data structure = topological collections
sequence, generalized array, (multi-)set, arbitrary graph, Delaunay triangulation, g-map, ..., cell complexes
 - Control structure = transformation
 - two powerful languages to specify sub-collections (elements in interaction)
 - Various rule application strategies: maximal parallel, asynchronous, stochastic, Gillespie-like, ...

Topological collection: representing the underlying space

Representation of space and structure

– Structure:

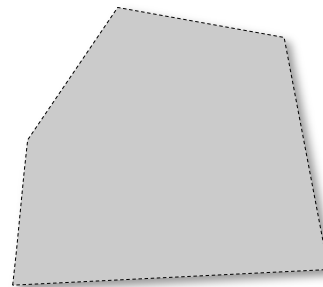
- Collection of *topological cells*



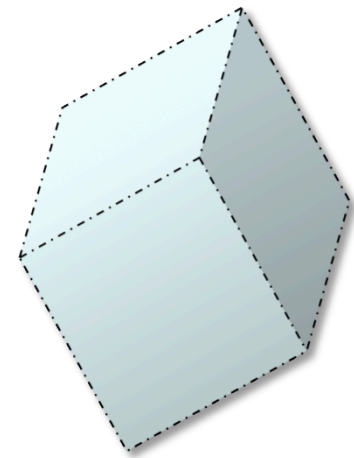
0-cell



1-cell



2-cell



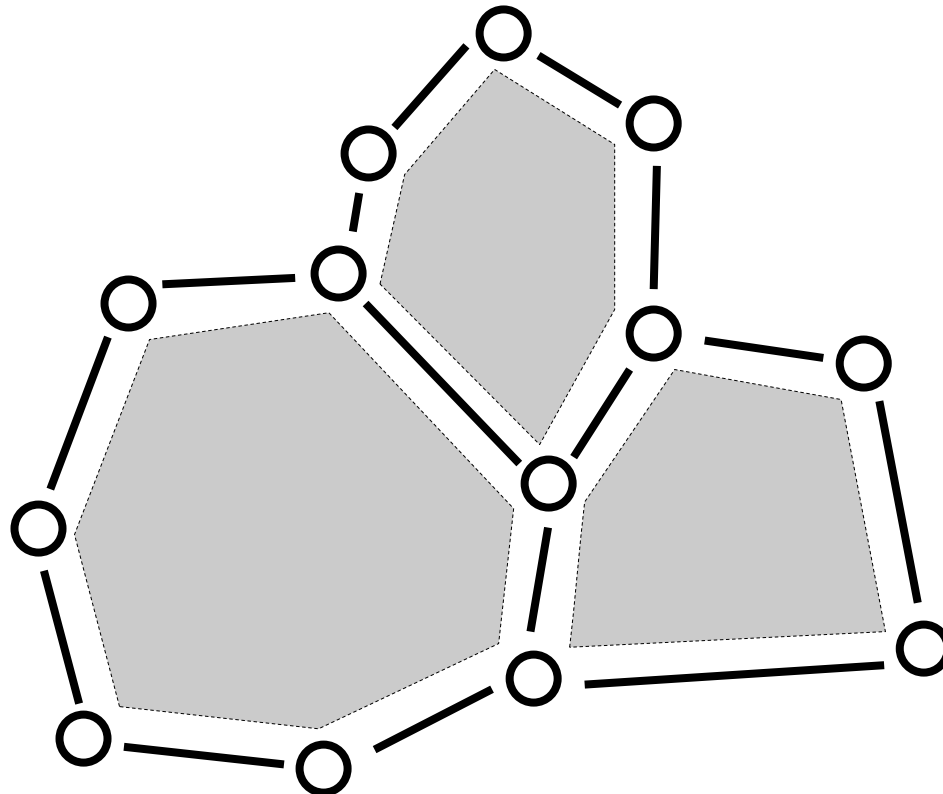
3-cell

Topological collection: representing the underlying space

Representation of space and structure

– Structure:

- Collection of topological cells
- *Incidence relationships*



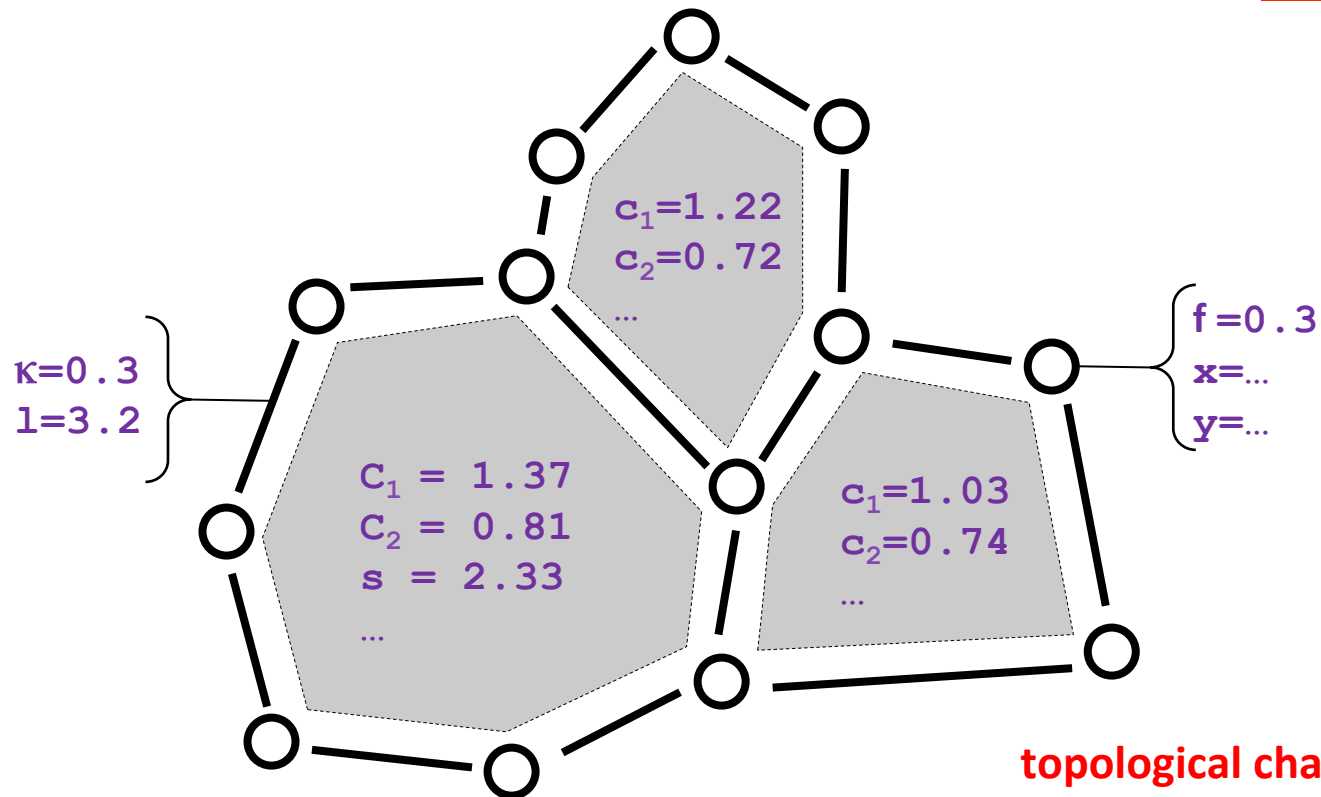
Topological collection: a data-field over topological cells

Representation of space and structure

– Structure:

- Collection of topological cells
- Incidence relationship

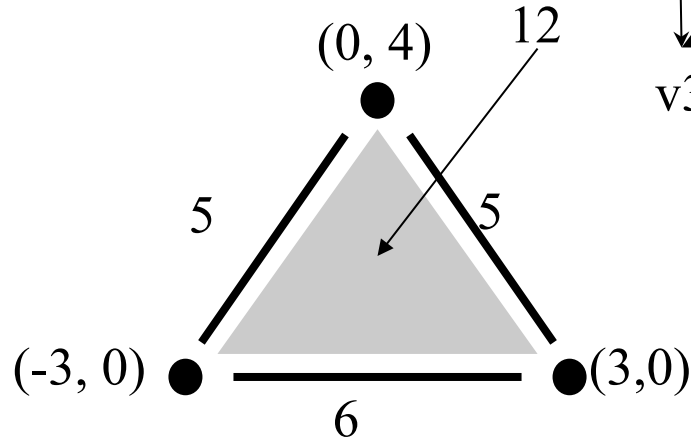
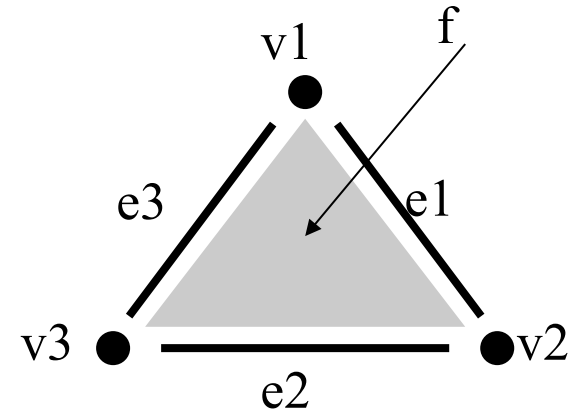
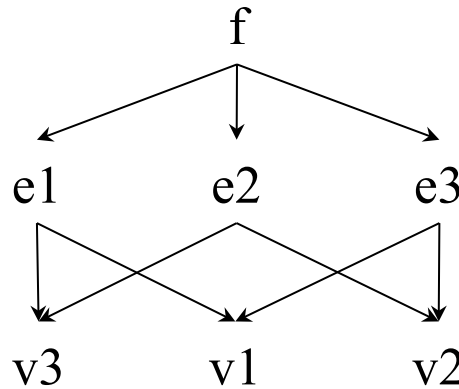
– Data : *associating values with topological cells* \approx field in physics



Abstract Simplicial Complex and simplicial chains

Incidence relationship and lattice of incidence:

- $\text{boundary}(f) = \{v_1, v_2, v_3, e_1, e_2, e_3\}$
- $\text{faces}(f) = \{e_1, e_2, e_3\}$
- $\text{cofaces}(v_1) = \{e_1, e_3\}$

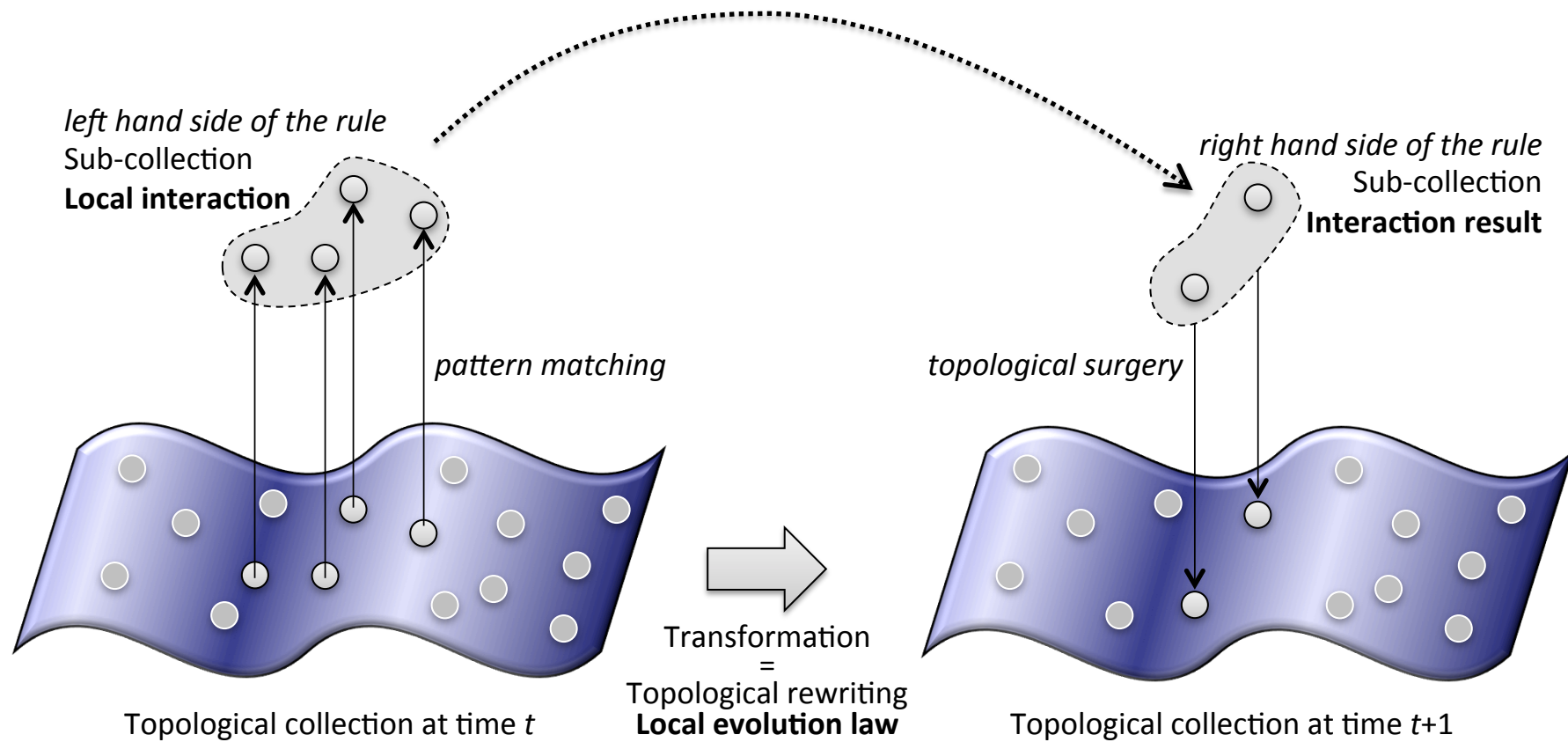


Topological chain

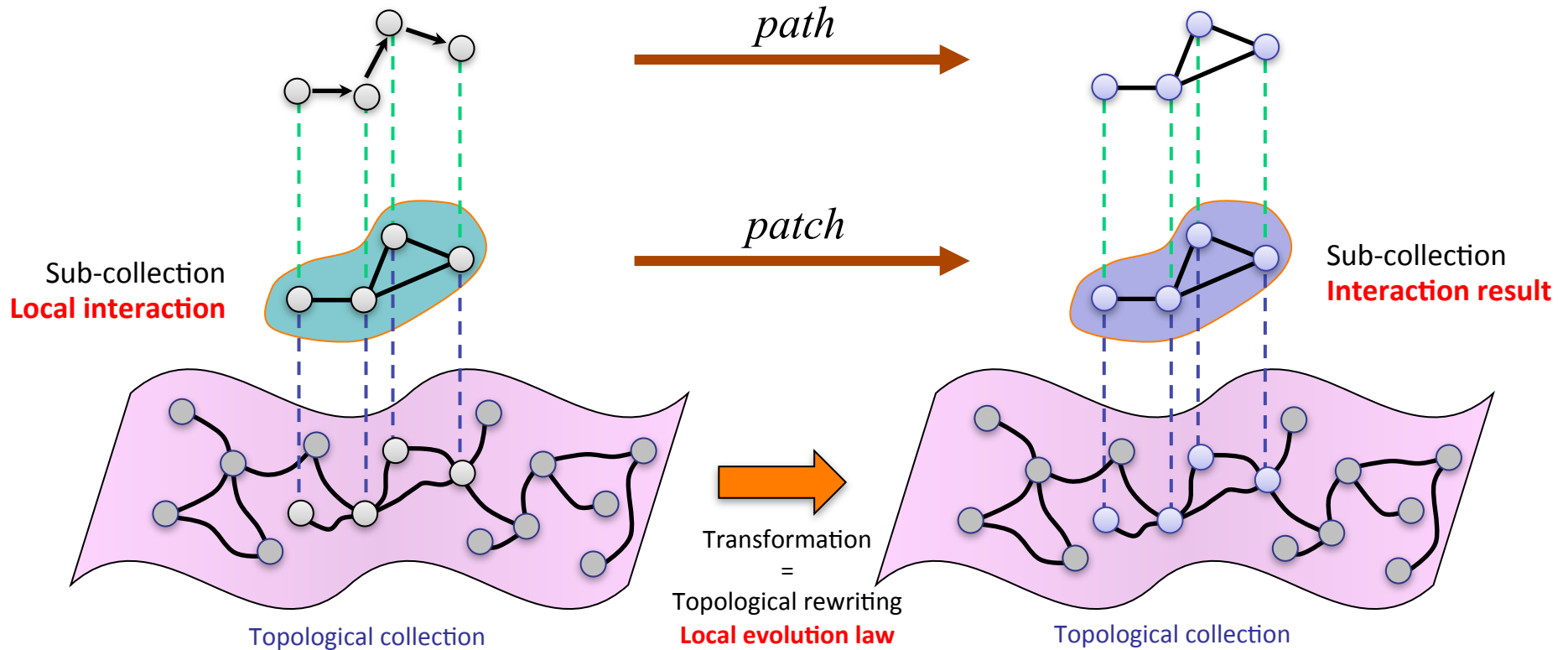
- coordinates with vertices
- lengths with edges
- area with f

$$\begin{pmatrix} 0 \\ 4 \end{pmatrix} \cdot v_1 + \begin{pmatrix} 3 \\ 0 \end{pmatrix} \cdot v_2 + \begin{pmatrix} -3 \\ 0 \end{pmatrix} \cdot v_3 + 5 \cdot e_1 + 6 \cdot e_2 + 5 \cdot e_3 + 12 \cdot f$$

Transformation



Transformation



Pattern matching : specifying a sub-collection of elements in interaction

- *Path transformation* (path = sequence of neighbor elements)
 - Concise but limited expressiveness
- *Patch transformation* (arbitrary shape)
 - Longer but higher expressiveness

Example: Diffusion Limited Aggregation (DLA)

- Diffusion: some particles are randomly diffusing; others are **fixed**
- Aggregation: if a **mobile** particle meets a **fixed** one, it stays fixed

```
trans dla = {  
  `mobile , `fixed => `fixed, `fixed ;  
  `mobile , <undef> => <undef>, `mobile  
}
```

NEIGHBOR OF

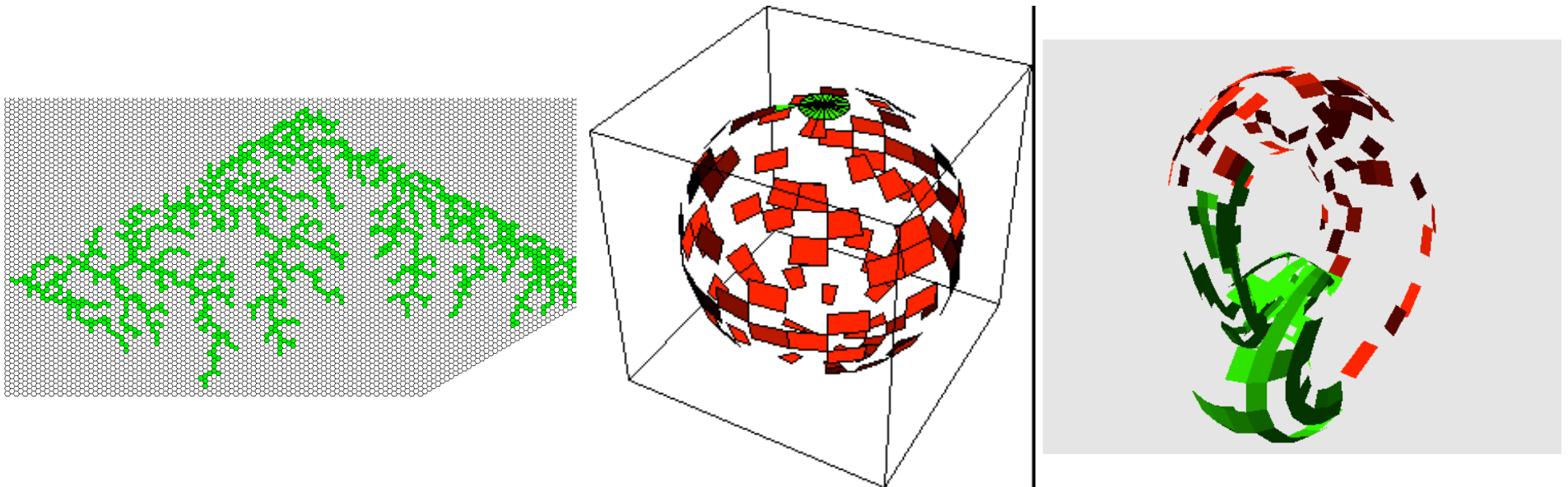


Example: Diffusion Limited Aggregation (DLA)

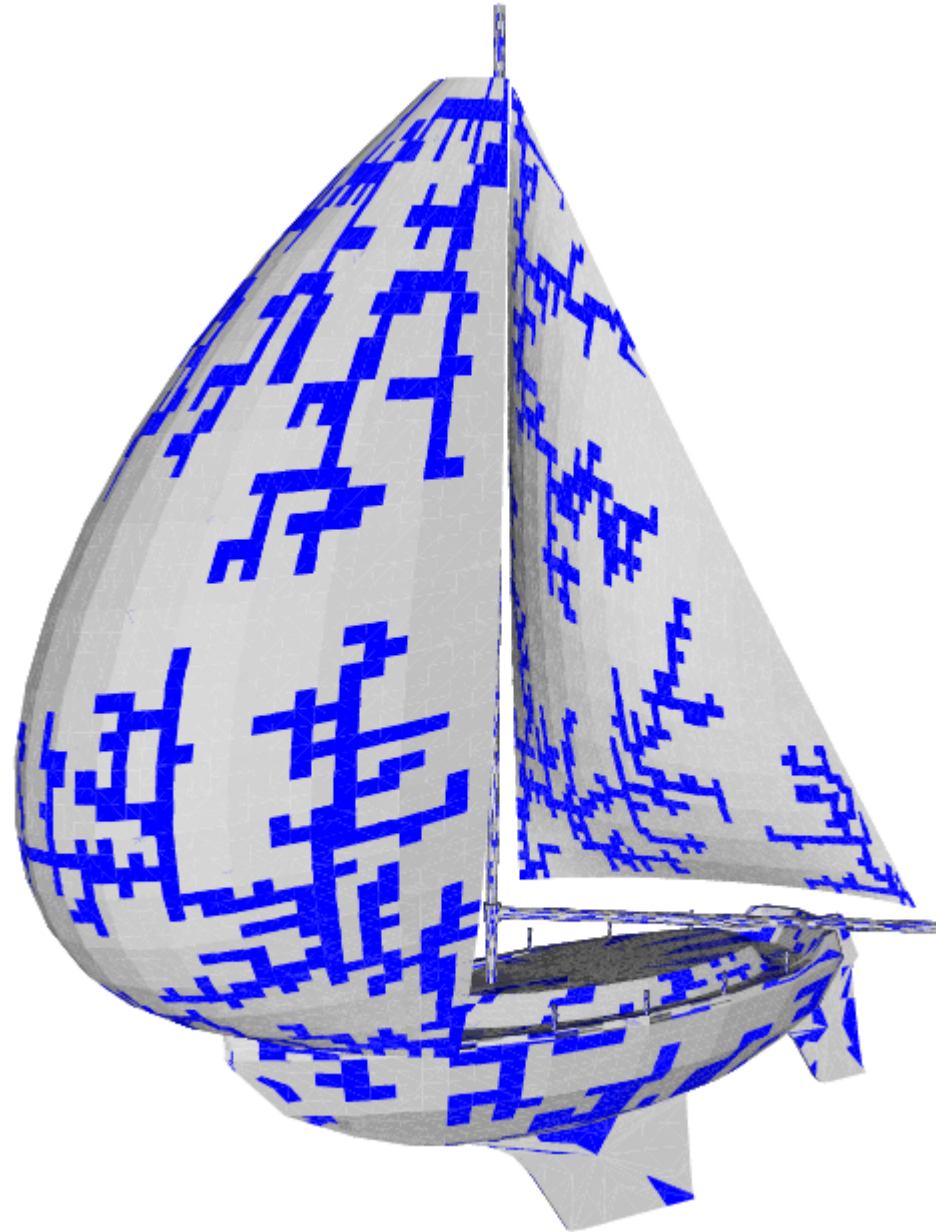
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}
```

this transformation is an abstract process that can be applied to any kind of space



Polytypisme



Transformation = rewriting labeled cell complexes

$1 + 2 \rightarrow \dots$ (arithmetic) term rewriting
↙
arithmetic operation

$a . b \rightarrow \dots$ string rewriting (\sim L systems)
↙
string concatenation

$2H + O \rightarrow H_2O$ multiset rewriting (\sim chemistry)
↙
multiset concatenation (= the chemical soup)

$V_1 \cdot \sigma_1 + V_2 \cdot \sigma_2 \rightarrow \dots$ **topological rewriting (MGS)**
↙
gluing cell in a cell complex

Trees and spatial structure

- **Associative-commutative term rewriting**

= multiset

= *chemical soup*

= **chemical computing, P systems**

- **Associative term rewriting**

= string

= *linear structure*

= **DNA computing, splicing systems**

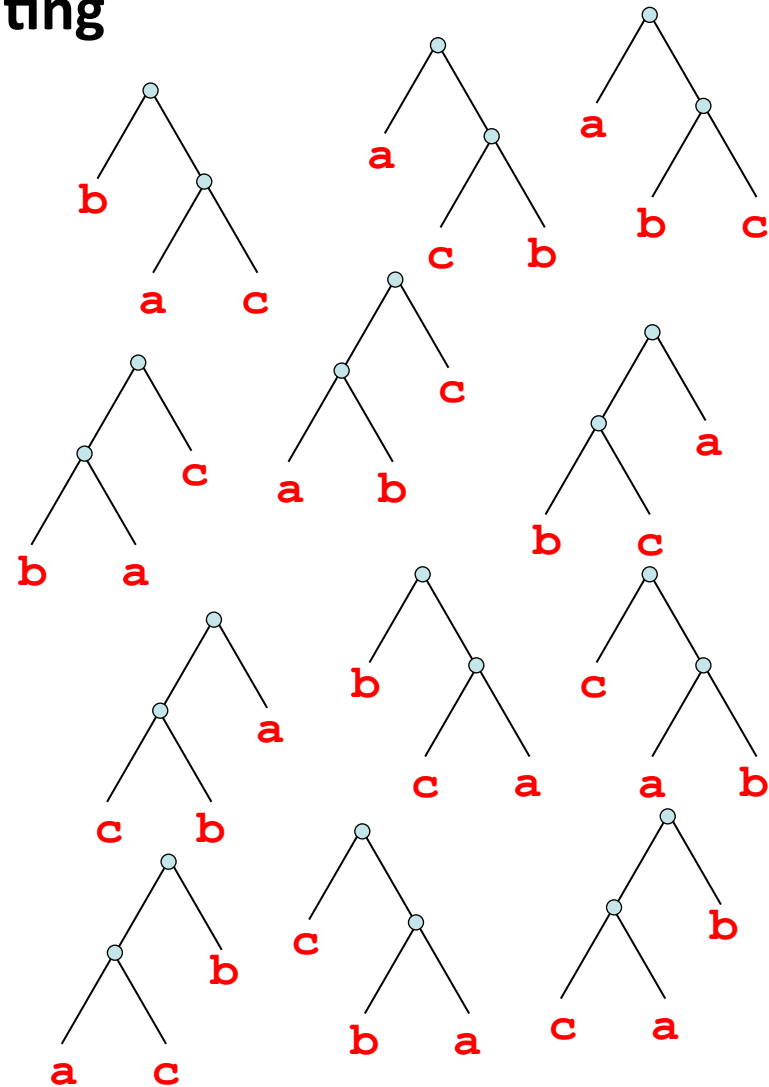
- **Term rewriting**

= tree

= *branching 1D structure*

= **L systems**

AC = stirring



$$a(bc) = a(cb) = b(ac) = b(ca) = c(ab) = c(ba) = (ab)c = (ac)b = (ba)c = (bc)a = (ca)b = (cb)a$$

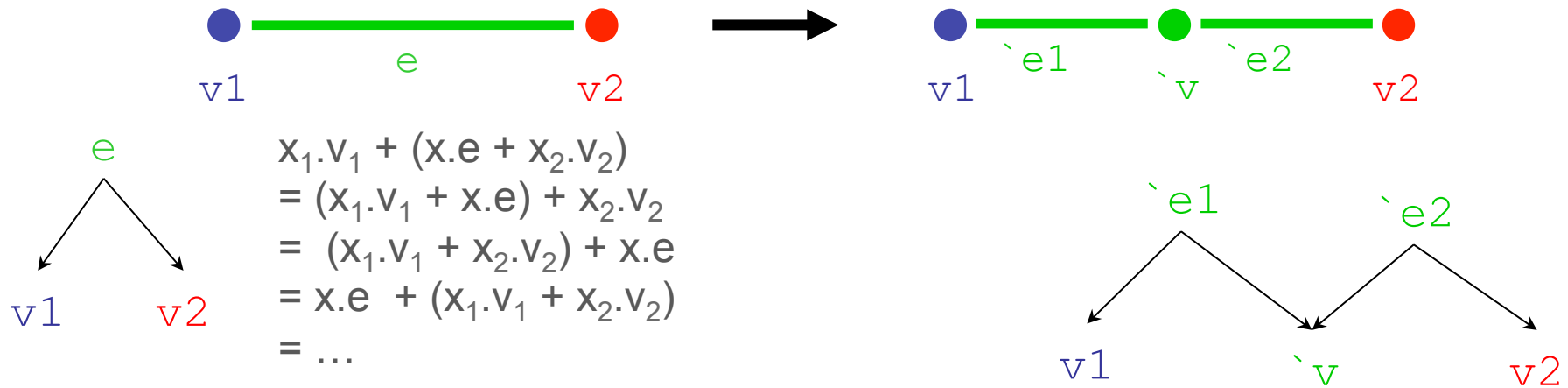
$$a(bc) = (ab)c$$

$$(a(bc)) \neq (ab)c$$

Topological rewriting \neq graph rewriting

$v_1 \cdot \sigma_1 + v_2 \cdot \sigma_2 \rightarrow \dots$ **topological rewriting (MGS)**

the structure is in the cells σ not in $+$



$v_1 < e : [\text{dim} = 1] > v_2 \Rightarrow$

v_1

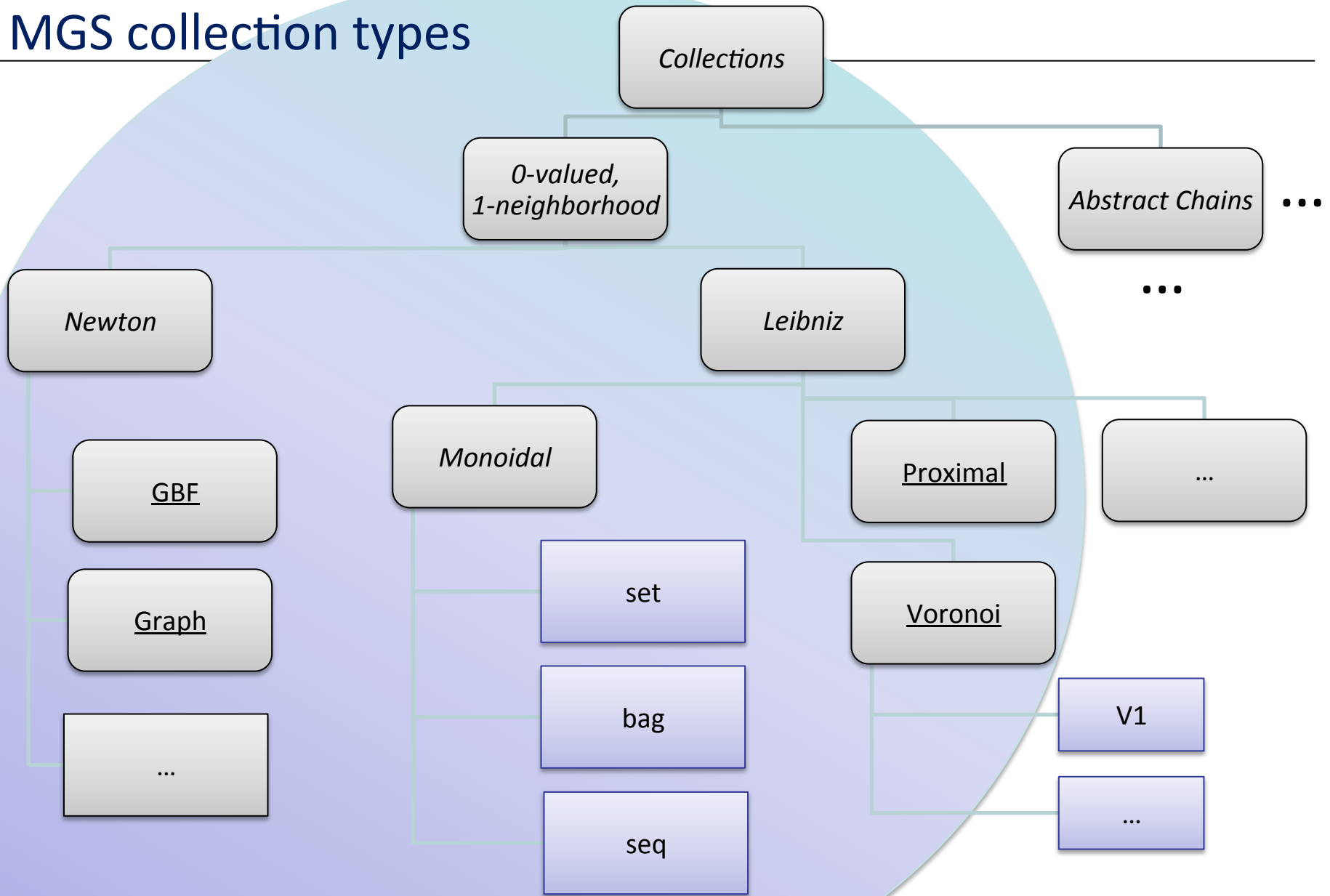
$\text{`e1} : [\text{dim} = 1, \text{ faces} = (\wedge v_1, \text{`v}), \text{ val} = \dots]$

$\text{`v} : [\text{dim} = 0, \text{ cofaces} = (\text{`e1}, \text{`e2}), \text{ val} = (v_1 + v_2) / 2]$

$\text{`e2} : [\text{dim} = 1, \text{ faces} = (\wedge v_2, \text{`v}), \text{ val} = \dots]$

v_2

MGS collection types



Leibniz: $x \Rightarrow \langle \text{undef} \rangle$ means delete x

Newton: $x \Rightarrow \langle \text{undef} \rangle$ means an undefined value @ x

Abstract type

Type constructor

Concrete type

***0-valued, 1-neighborhood* Collection**

Graph = 1D Simplicial Complex

- Vertices are labeled
- The neighborhood is defined by the edge of a graph

- Isolated graphs (no edges) : record
- Complete graphs : set and multisets
- Linear:
 - sequence (list)
 - ring
- Uniform graphs: Cayley graphs
the graphical representation of a group presentation
- Graph defined by a distance:
 - proximal
 - delaunay

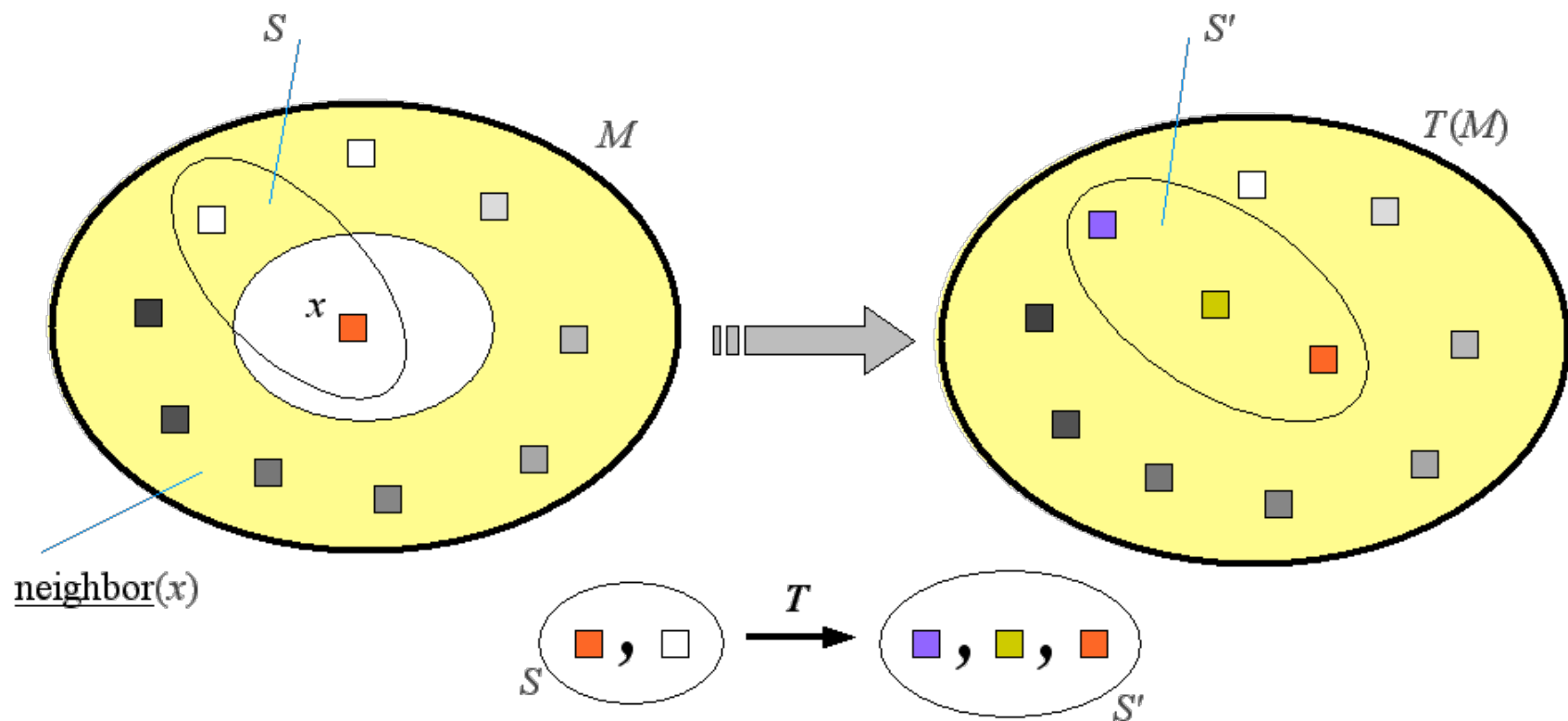
Complete graphs, multiset and concrete topology

collection = multiset M

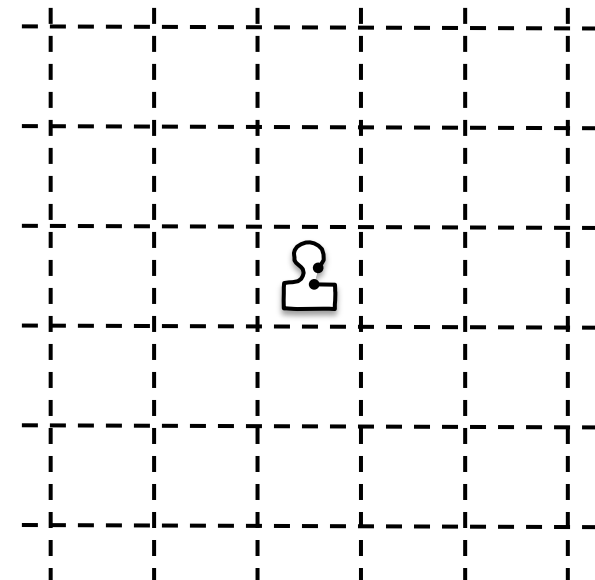
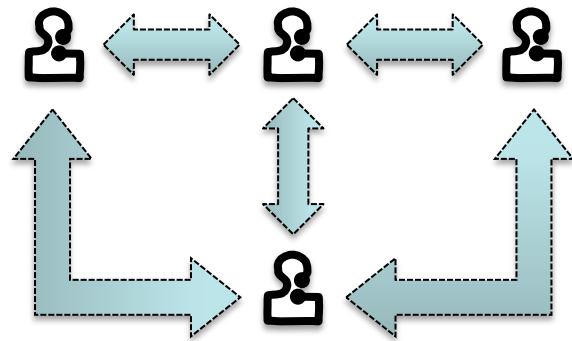
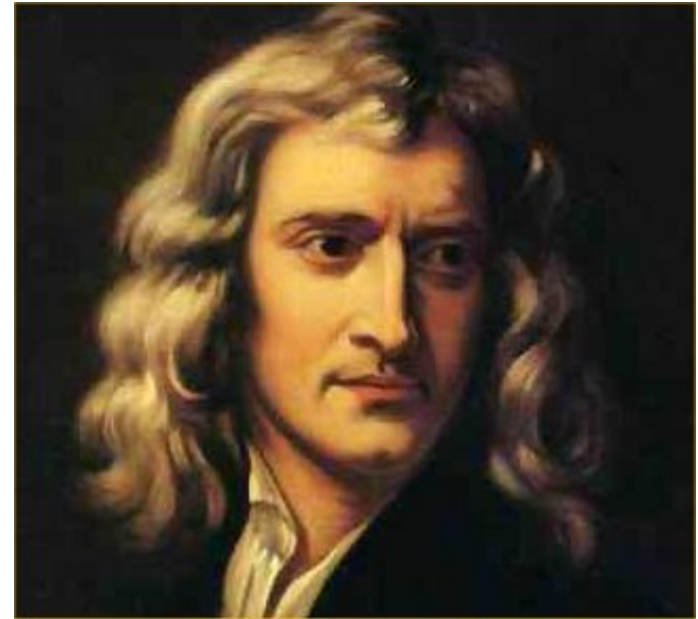
topology : $\text{neighbor}(x) = M - \{x\}$ any element is neighbor of any other element

subcollection $S = \text{prefixe of an orbite of } \text{neighbor} = \text{multiset}$

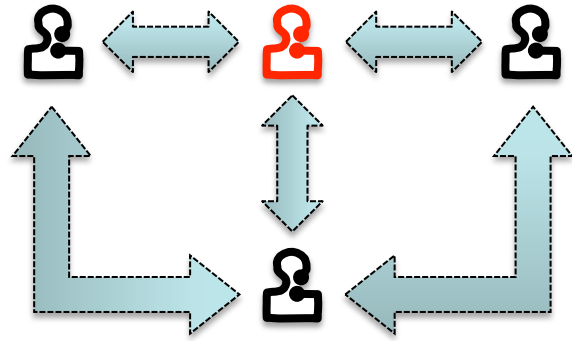
$\text{boundary}(S) = S$.



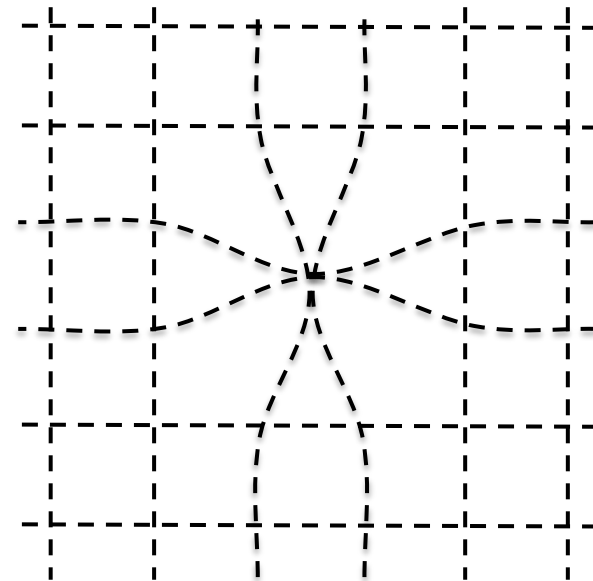
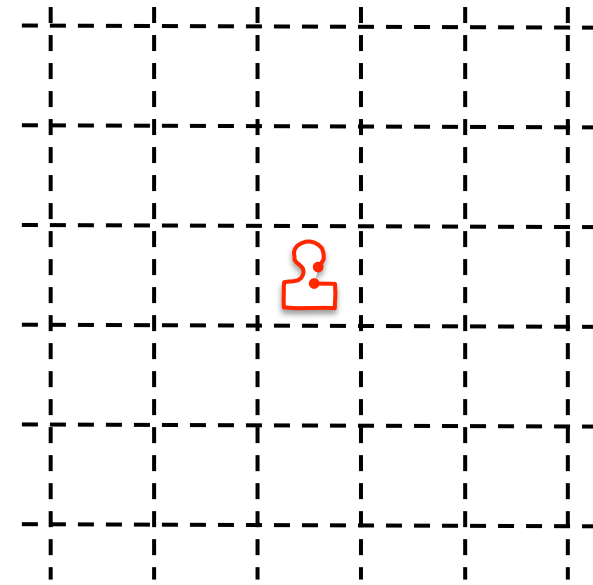
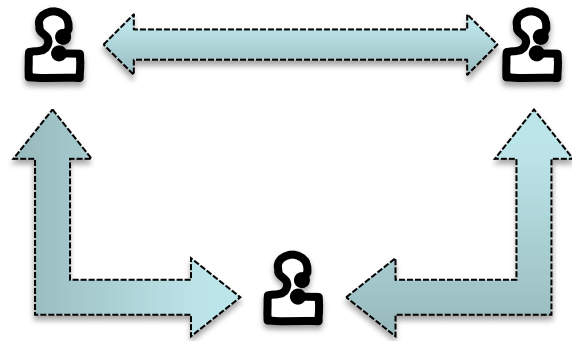
Leibniz vs. Newton



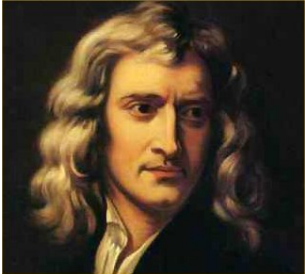
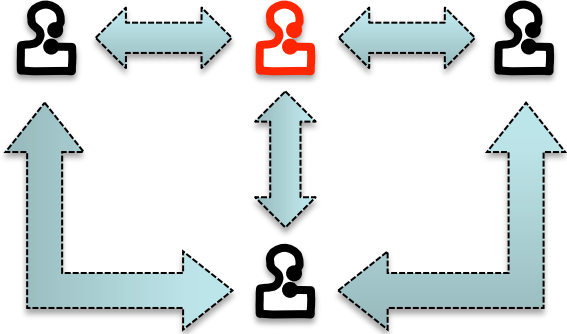
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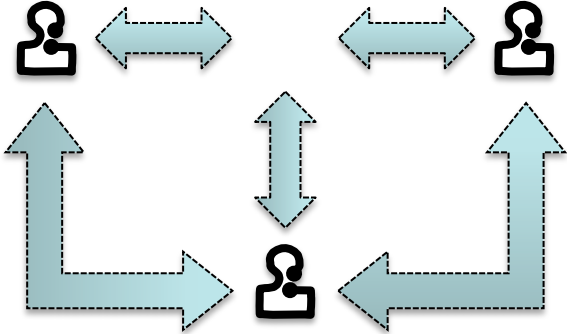
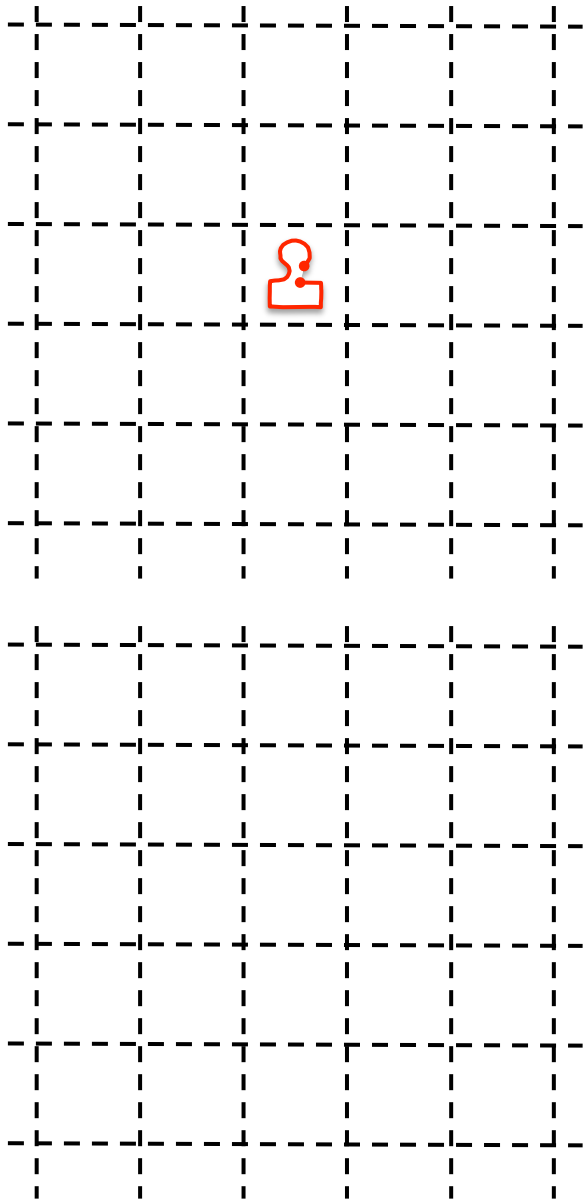
$x \Rightarrow \cdot$



Leibniz vs. Newton



$x \Rightarrow \cdot$





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